



# Evolutionary Clustering

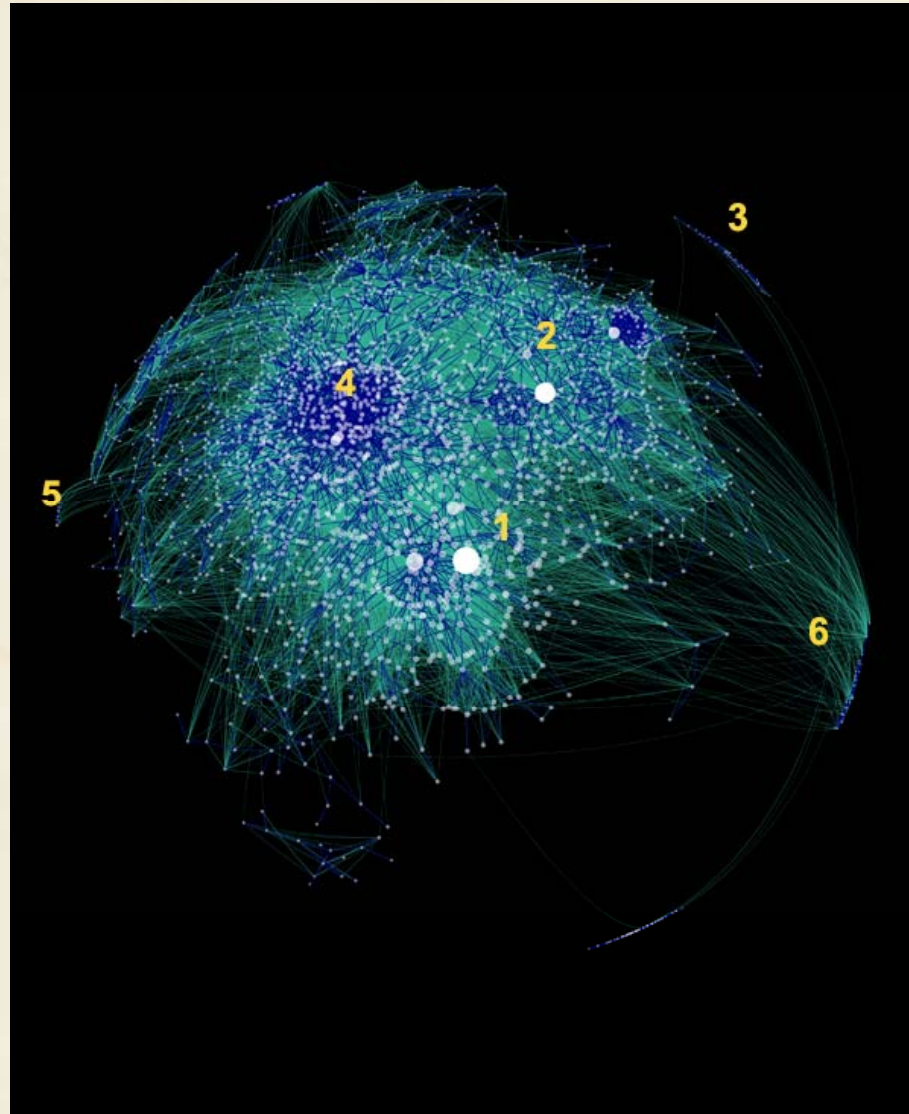
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# Evolutionary Clustering

- Processing time stamped data to produce a sequence of clustering.
- Each clustering should be similar to the history, while accurate to reflect corresponding data.
- Trade-off between long-term concept drift and short-term variation.

# Example I: Blogosphere





# Blogosphere

- Community detection
- The overall interest and friendship network is drift slowly.
- Short-term variation is triggered by external event.

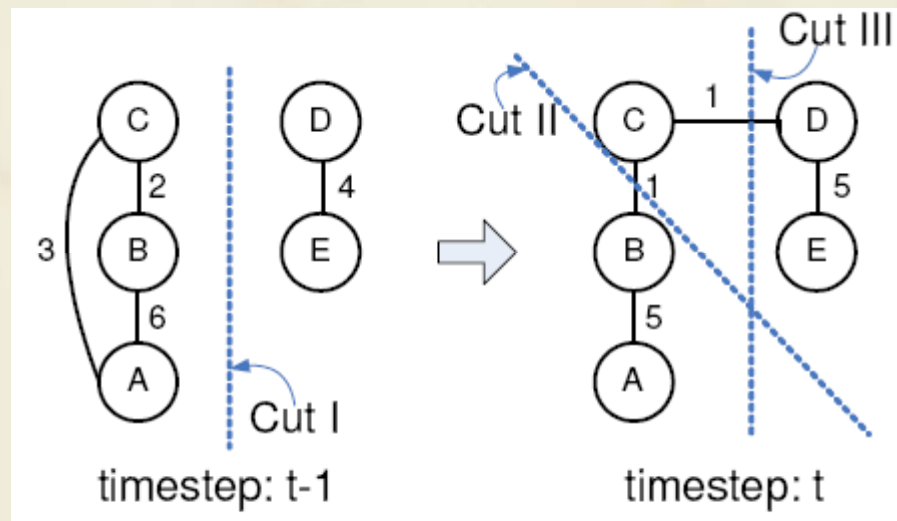
## Example II



- Moving objects equipped with GPS sensors are to be clustered (for *traffic jam prediction* or *animal migration analysis*)
- The object follow certain route in the long-term.
- Its estimated coordinate at a given time may vary due to limitations on bandwidth and sensor accuracy.

# The goal

- Current clusters should mainly depend on the current data features.
- Data is expected to change not too quickly. (**Temporal Smoothness**)





# Related Work

- Online document clustering mainly focusing on **novelty detection**.
- Clustering data streams: **scalability and one-pass-access**.
- Incremental clustering: **efficiently apply dynamic updates**.
- Constrained clustering: **must link/can-not link**.
- Evolutionary Clustering:
  - The similarity among existing data points varies with time.
  - How cluster evolves smoothly.

# Basic framework

- Snapshot quality:  $\text{sq}(C_t, M_t)$
- History cost:  $\text{hc}(C_t, C_{t-1})$
- The total quality of a *cluster sequence*

$$\sum_{t=1}^T \text{sq}(C_t, M_t) - \text{cp} \cdot \sum_{t=2}^T \text{hc}(C_{t-1}, C_t),$$

- We try to find an optimal cluster sequence greedily without knowing the future.
- Each step, find a cluster that maximize

$$\text{sq}(C_t, M_t) - \text{cp} \cdot \text{hc}(C_{t-1}, C_t).$$





# Construct the similarity matrix

- Local Information Similarity

$$\mathcal{R}(t) = (1 - \beta) \cdot \mathcal{B}(t)\mathcal{B}'(t) + \beta \cdot \mathcal{R}(t - 1), \quad \text{for } t > 0$$

- Temporal Similarity

$$\text{Corr}(i, j, t_0) = \frac{\sum_{t=1}^{t_0} (x_{i,t} - \mu(i, t))(x_{j,t} - \mu(j, t))}{\sqrt{\text{Var}(i, t) \cdot \text{Var}(j, t)}},$$

- Total Similarity

$$M_t(i, j) = \alpha \cdot S_t(i, j) + (1 - \alpha) \cdot \text{Corr}(i, j, t),$$

# Instantiations I: K-means

- Snapshot quality:  $\text{sq}(C, M) = \sum_{x \in U} (1 - \min_{c \in C} \|c - x\|)$ .
- History cost:  $\text{hc}(C, C') = \min_{f: [k] \rightarrow [k]} \|c_i - c'_{f(i)}\|$ ,
- In each k-means iteration, the new centroid between the centroid suggested by non-evolutionary k-means and its closest match from previous time step.

where

$$c_j^t \leftarrow (1 - \gamma) \cdot c_p^{t-1} + \gamma \cdot \mathbb{E}_{x \in \text{closest}(j)} (x).$$
$$\gamma = n_j^t / (n_j^t + n_{f(j)}^{t-1})$$

# Agglomerative Clustering

- This is more complicated: need to find out the cluster similarity between two trees ( $T, T'$ ).
- Snapshot quality: the sum of the qualities of all merges performed to create  $T$ .
- History cost:
- 4 greedy heuristics (skipped here):

$$hc(T', T) = \sum_{\substack{i, j \in \text{leaf}(T') \\ i \neq j}} (d_{T', T}(i, j)).$$

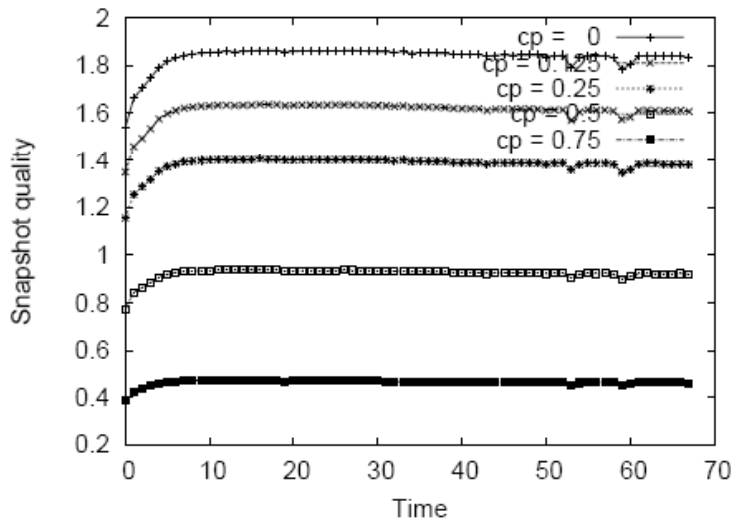
– Squared:

$$\text{sim}_M(m) = \left( cp \cdot \sum_{\substack{i \in \text{leaf}(m_\ell) \\ j \in \text{leaf}(m_r)}} (d_{T', T}(i, j)) \right).$$

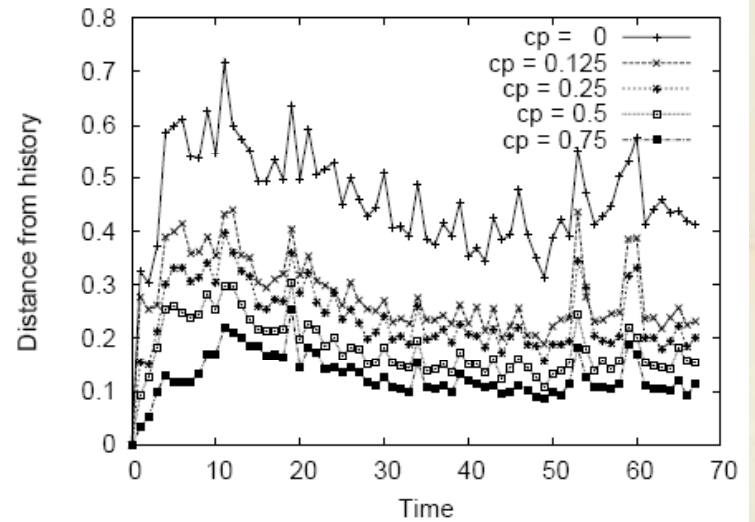


# Experiment Setup

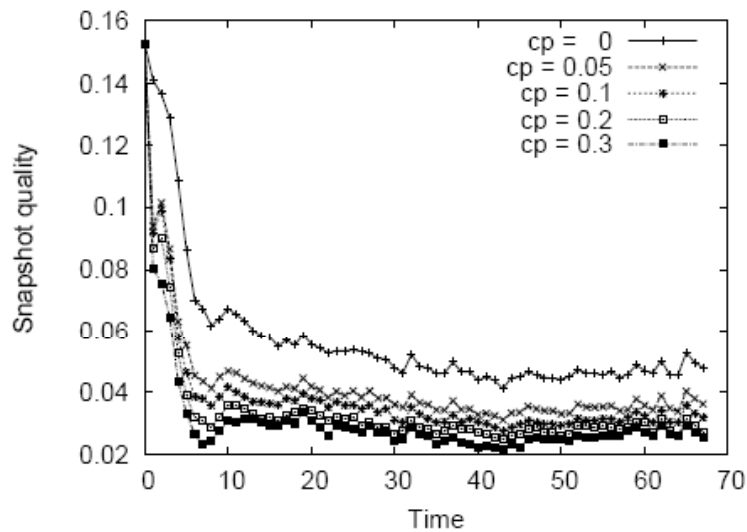
- Data: photo-tag pairs from flickr.com
- Task: Cluster tags
- Two tags are similar if they both occur at the same photo
- However, the experiments in the paper doesn't make much sense for me



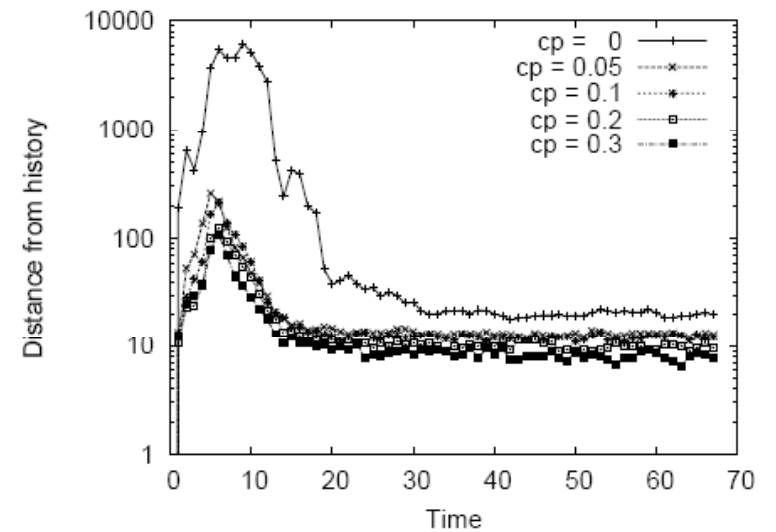
(a) Snapshot quality over time



(b) Distance from history, over time



(a) Linear-Both snapshot quality (log-linear)



(b) Linear-Both distance from history (log-linear)



# Comments

- Pros:
  - New problem
  - Effective heuristics
  - Temporal smoothness is incorporated in both the affinity matrix and the history cost.
- Cons
  - No global solution.
  - Can not handle the change of number of clusters.
  - Experiment seems unreasonable.



# Evolutionary Spectral Clustering

- Idea is almost the same, but here focus on **spectral clustering**, which preserves nice properties (global solution to a relaxed cut problem, connections to k-means).
- But the idea is presented clearer here.

$$Cost = \alpha \cdot CS + \beta \cdot CT$$

- How to measure the temporal smoothness?
  - Measure the cluster quality on past data
  - Compare the cluster membership

# Spectral Clustering (1)

- K-way average association:  $AA = \sum_{l=1}^k \frac{assoc(\mathcal{V}_l, \mathcal{V}_l)}{|\mathcal{V}_l|}$

- Negated Average Association:

$$NA = Tr(W) - AA = Tr(W) - \sum_{l=1}^k \frac{assoc(\mathcal{V}_l, \mathcal{V}_l)}{|\mathcal{V}_l|}$$

- Normalized Cut:

$$NC = \sum_{l=1}^k \frac{assoc(\mathcal{V}_l, \mathcal{V} \setminus \mathcal{V}_l)}{assoc(\mathcal{V}_l, \mathcal{V})}$$

- The basic objective is to minimize the normalized cut or negated average association.





# Spectral Clustering (2)

- Typical Procedures
  - Compute eigenvectors  $X$  of some variations of the similarity matrix
  - Project all data points into  $\text{span}(X)$
  - Applying k-means algorithm to the projected data points to obtain the clustering result.

# K-means Clustering

- Find a partition  $\{v_1, v_2, \dots, v_k\}$  to minimize the following:

$$KM = \sum_{l=1}^k \sum_{i \in \mathcal{V}_l} \|\vec{v}_i - \vec{\mu}_l\|^2$$

# Preserving Cluster Quality

- K-means

$$\begin{aligned} Cost_{KM} &= \alpha \cdot CS_{KM} + \beta \cdot CT_{KM} \\ &= \alpha \cdot KM_t |_{Z_t} + \beta \cdot KM_{t-1} |_{Z_t} \\ &= \alpha \cdot \sum_{l=1}^k \sum_{i \in \mathcal{V}_{l,t}} \|\vec{v}_{i,t} - \vec{\mu}_{l,t}\|^2 \\ &\quad + \beta \cdot \sum_{l=1}^k \sum_{i \in \mathcal{V}_{l,t}} \|\vec{v}_{i,t-1} - \vec{\mu}_{l,t-1}\|^2 \end{aligned}$$

Check whether  
current cluster fits  
previous cluster.

- A hidden problem, still needs to find the cluster mapping.

# Negated Average Association(1)

- Similar to K-means strategy:

$$\begin{aligned} Cost_{NA} &= \alpha \cdot CS_{NA} + \beta \cdot CT_{NA} \\ &= \alpha \cdot NA_t |_{Z_t} + \beta \cdot NA_{t-1} |_{Z_t} \end{aligned}$$

- As we know,  $NA = Tr(W) - Tr(\tilde{Z}^T W \tilde{Z})$   
where  $Z^T Z = I_k$ ,

$$\begin{aligned} Cost_{NA} &= \alpha \cdot [Tr(W_t) - Tr(\tilde{Z}_t^T W_t \tilde{Z}_t)] \quad (9) \\ &\quad + \beta \cdot [Tr(W_{t-1}) - Tr(\tilde{Z}_t^T W_{t-1} \tilde{Z}_t)] \\ &= Tr(\alpha W_t + \beta W_{t-1}) - Tr[\tilde{Z}_t^T (\alpha W_t + \beta W_{t-1}) \tilde{Z}_t] \end{aligned}$$

So we just need to maximize the 2nd term.

# Negated Average Association(2)

- The solution to  $Tr \left[ \tilde{Z}_t^T (\alpha W_t + \beta W_{t-1}) \tilde{Z}_t \right]$  are actually the largest k eigenvectors of the matrix.
- Notice that the solution is optimal in terms of a relaxed problem.
- Connection to k-means.
- It is shown that k-means can be reformulated as

$$KM = Tr(A^T A) - Tr(\tilde{Z}^T A^T A \tilde{Z})$$

So k-means is actually a special case of negated average association with a specific similarity definition.

# Normalized Cut

- Normalized cut can be represented as

$$NC = k - \text{Tr} \left[ Y^T \left( D^{-\frac{1}{2}} W D^{-\frac{1}{2}} \right) Y \right]$$

with certain constraints.

- Since  $Cost_{NC} = \alpha \cdot CS_{NC} + \beta \cdot CT_{NC}$   
 $= \alpha \cdot NC_t |_{Z_t} + \beta \cdot NC_{t-1} |_{Z_t}$
- We have

$$\begin{aligned} Cost_{NC} &\approx \alpha \cdot k - \alpha \cdot \text{Tr} \left[ X_t^T \left( D_t^{-\frac{1}{2}} W_t D_t^{-\frac{1}{2}} \right) X_t \right] & (13) \\ &+ \beta \cdot k - \beta \cdot \text{Tr} \left[ X_t^T \left( D_{t-1}^{-\frac{1}{2}} W_{t-1} D_{t-1}^{-\frac{1}{2}} \right) X_t \right] \\ &= k - \text{Tr} \left[ X_t^T \left( \alpha D_t^{-\frac{1}{2}} W_t D_t^{-\frac{1}{2}} + \beta D_{t-1}^{-\frac{1}{2}} W_{t-1} D_{t-1}^{-\frac{1}{2}} \right) X_t \right] \end{aligned}$$

Again a trace maximization problem.



# Discussion on PCQ framework

- Very intuitive
- The historic similarity matrix is scaled and combined with current similarity matrix.

# Preserving Cluster Membership

- Temporal cost is measured as the difference between current partition and historical partition.
- Use chi-square statistics to represent the distance:

$$\chi^2(Z_t, Z_{t-1}) = n \left( \sum_{i=1}^k \sum_{j=1}^k \frac{|\mathcal{V}_{ij}|^2}{|\mathcal{V}_{i,t}| \cdot |\mathcal{V}_{j,t-1}|} - 1 \right)$$

So for K-means

$$Cost_{KM} = \alpha \cdot CS_{KM} + \beta \cdot CT_{KM} \quad (15)$$

$$= \alpha \cdot \sum_{l=1}^k \sum_{i \in \mathcal{V}_{l,t}} \|\bar{v}_{i,t} - \bar{\mu}_{l,t}\|^2 - \beta \cdot \sum_{i=1}^k \sum_{j=1}^k \frac{|\mathcal{V}_{ij}|^2}{|\mathcal{V}_{i,t}| \cdot |\mathcal{V}_{j,t-1}|}$$



# Negated Average Association(1)

- Distance:  $dist(X_t, X_{t-1}) = \frac{1}{2} \|X_t X_t^T - X_{t-1} X_{t-1}^T\|^2$

- So

$$\begin{aligned} Cost_{NA} &= \alpha \cdot CS_{NA} + \beta \cdot CI_{NA} && (17) \\ &= \alpha \cdot [Tr(W_t) - Tr(X_t^T W_t X_t)] + \frac{\beta}{2} \cdot \|X_t X_t^T - X_{t-1} X_{t-1}^T\|^2 \\ &= \alpha \cdot [Tr(W_t) - Tr(X_t^T W_t X_t)] + \\ &\quad \frac{\beta}{2} Tr \left( X_t X_t^T - X_{t-1} X_{t-1}^T \right)^T \left( X_t X_t^T - X_{t-1} X_{t-1}^T \right) \\ &= \alpha \cdot [Tr(W_t) - Tr(X_t^T W_t X_t)] + \\ &\quad \frac{\beta}{2} Tr(X_t X_t^T X_t X_t^T - 2X_t X_t^T X_{t-1} X_{t-1}^T + X_{t-1} X_{t-1}^T X_{t-1} X_{t-1}^T) \\ &= \alpha \cdot [Tr(W_t) - Tr(X_t^T W_t X_t)] + \beta k - \beta Tr \left( X_t^T X_{t-1} X_{t-1}^T X_t \right) \\ &= \alpha \cdot Tr(W_t) + \beta \cdot k - Tr \left[ X_t^T (\alpha W_t + \beta X_{t-1} X_{t-1}^T) X_t \right] \end{aligned}$$

# Negated Average Association(2)

- It can be shown that the unrelaxed partition:

$$\frac{1}{2} \|\tilde{Z}_t \tilde{Z}_t^T - \tilde{Z}_{t-1} \tilde{Z}_{t-1}^T\|^2 = k - \sum_{i=1}^k \sum_{j=1}^k \frac{|\mathcal{V}_{ij}|^2}{|\mathcal{V}_{i,t}| \cdot |\mathcal{V}_{j,t-1}|} \quad (18)$$

- So negated average association can be applied to solve the original evolutionary k-means

# Normalized Cut

- Straight forward

$$\begin{aligned} Cost_{NC} &= \alpha \cdot CS_{NC} + \beta \cdot CT_{NC} && (19) \\ &= \alpha \cdot k - \alpha \cdot Tr \left[ X_t^T \left( D_t^{-\frac{1}{2}} W_t D_t^{-\frac{1}{2}} \right) X_t \right] \\ &\quad + \frac{\beta}{2} \cdot \|X_t X_t^T - X_{t-1} X_{t-1}^T\|^2 \\ &= k - Tr \left[ X_t^T \left( \alpha D_t^{-\frac{1}{2}} W_t D_t^{-\frac{1}{2}} + \beta X_{t-1} X_{t-1}^T \right) X_t \right] \end{aligned}$$

# Comparing PQC & PCM

- As for the temporal cost,
  - In PCQ, we need to maximize

$$\text{Tr}(X_t^T W_{t-1} X_t)$$

- In PCM, we need to maximize

$$\text{Tr}(X_t^T X_{t-1} X_{t-1}^T X_t)$$

- Connection:

$$X_t^T W_{t-1} X_t = X_t^T (X_{t-1}, X_{t-1}^\perp) \Lambda_{t-1} (X_{t-1}, X_{t-1}^\perp)^T X_t$$

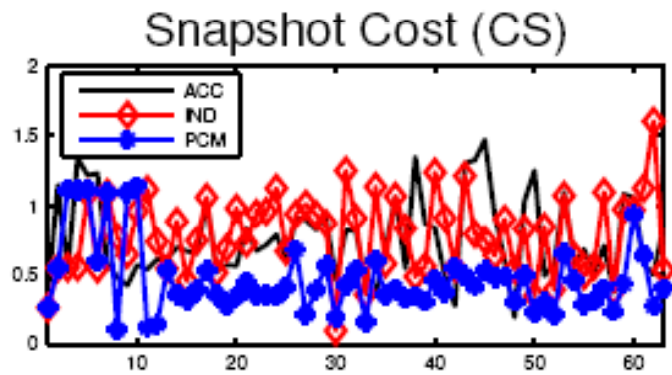
- In PCQ, all the eigen vectors are considered and penalized according to the eigen values.



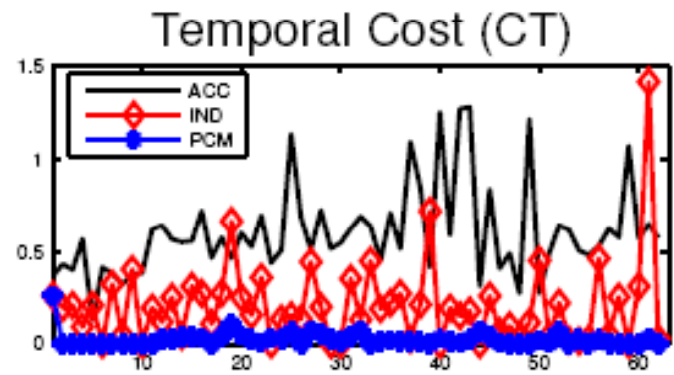
# Real Blog Data

- 407 blogs during 63 consecutive weeks.
- 148,681 links.
- Two communities (ground truth, labeled manually based on contents)
- Affinity matrix is constructed based on links

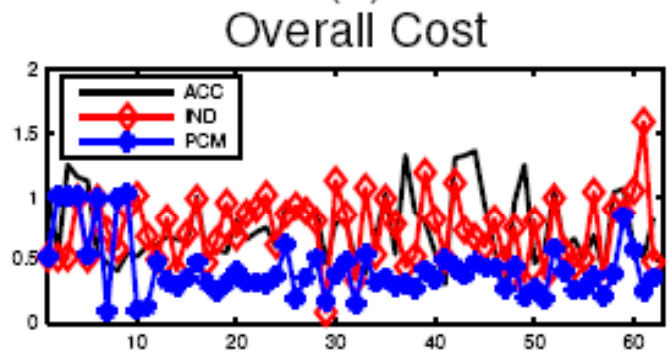
# Experiment Result



(a)

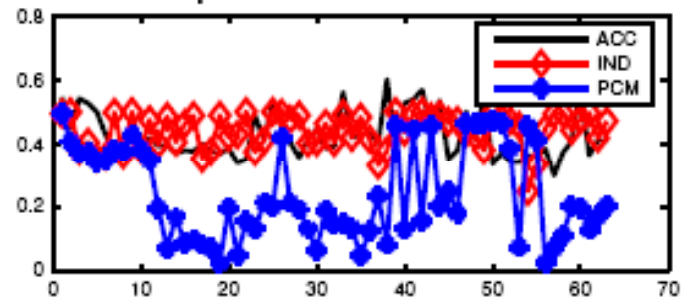


(b)



(c)

Error Compared to the Ground Truth



(d)



# Comments

- Nice formulation which has a global solution for the relaxed version.
- Strong connection between k-means and negated average association.
- Can handle new objects or change of number of clusters.

Any Questions?

# Evolution

